

Acyclic Orders, Partition Schemes and CSPs

Unified Hardness Proofs and Improved Algorithms

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Short Summary

- Many computational problems can be realized as CSPs with infinite domains over partition schemes.
- Applications in AI include formalisms for qualitative spatial and temporal reasoning: *RCC-8*, *Allen's Interval Algebra*, *Rectangle Algebra*, etc.
- Many CSPs over partition schemes are computationally hard.
- We provide sufficient conditions for hardness explaining many results in the literature in a uniform way.
- We show that even restricted to degree-bounded cases, such CSPs are unlikely to admit subexponential time algorithms.
- In special cases (e.g., *RCC-8*) we show that CSPs over partition schemes admit improved algorithms.

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Let \mathcal{B} be a set of binary relations over a domain D .

CSP(\mathcal{B})

INSTANCE: A set of variables V and a set of constraints C of form $R(x, y)$, where $x, y \in V$ and $R \in \mathcal{B}$.

QUESTION: Is there an assignment $f: V \rightarrow D$ such that $(f(x), f(y)) \in R$ for all constraints $R(x, y)$ in C ?

If $(f(x), f(y)) \in R$, we say that assignment f *satisfies* $R(x, y)$.

A *partition scheme* \mathcal{B} is a set of binary relations over an infinite domain D such that:

- $\bigcup_{R \in \mathcal{B}} R = D^2$ (jointly exhaustive).
- If $R_1, R_2 \in \mathcal{B}$, then $R_1 \cap R_2 = \emptyset$ (pairwise disjoint).
- $\{(d, d) \mid d \in D\} \in \mathcal{B}$ (equality).
- If $R \in \mathcal{B}$, then $\{(b, a) \mid (a, b) \in R\} = R^{-1} \in \mathcal{B}$ (inverses).

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Example 1

$\langle \mathbb{Q}; =, \neq \rangle$.

- ✓ jointly exhaustive
- ✓ pairwise disjoint
- ✓ contains equality
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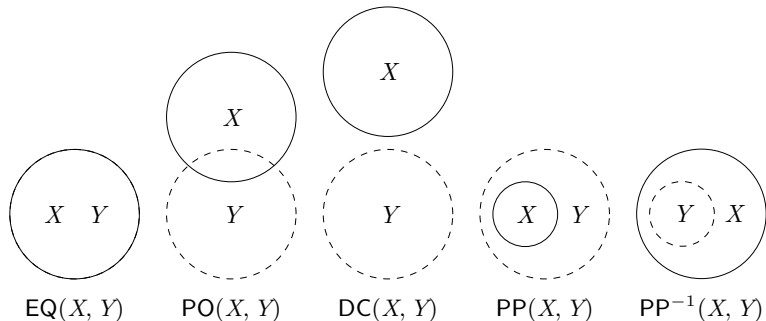
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Example 3: RCC-5

Objects of RCC-5 are (not necessarily connected) space regions.



More Expressive Power

Let $\mathcal{B}^{\vee=}$ contain unions of all relations in \mathcal{B} .

Example

The relation $\text{DR} \cup \text{PO}$ denoted by (DR, PO) contains pairs of regions that are either disjoint or overlap. Constraint $(\text{DR}, \text{PO})(X, Y)$ is logically equivalent to $\text{DR}(X, Y) \vee \text{PO}(X, Y)$.

$\mathcal{B}^{\vee=}$ has more expressive power than \mathcal{B} . However, $\text{CSP}(\mathcal{B}^{\vee=})$ is usually computationally hard.

Complexity Questions

- 1 For which partition schemes \mathcal{B} is $\text{CSP}(\mathcal{B}^{\vee=})$ NP-hard?
- 2 How much time is required to solve $\text{CSP}(\mathcal{B}^{\vee=})$?
- 3 Are there better algorithms for *some* partition schemes \mathcal{B} ?

An order $\prec \subseteq D^2$ is a binary relation.

- Irreflexive: $\nexists d \in D : d \prec d$.
- Transitive: $\forall d_1, d_2, d_3 : d_1 \prec d_2 \wedge d_2 \prec d_3 \implies d_1 \prec d_3$.
- Acyclic: $\nexists d_1, \dots, d_k : d_1 \prec d_2 \prec \dots \prec d_{k-1} \prec d_k \prec d_1$.
- Total: $\forall d_1, d_2 : d_1 \prec d_2 \vee d_2 \prec d_1$.
- Irreflexive + transitive = strict partial \implies acyclic.
- Irreflexive + transitive + total = strict total.

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Hardness Conditions

Let $\prec \subseteq D^2$ be an acyclic order and $\sqcap \subseteq D^2$ be a relation.

(C1) (unbounded total orders)

$\forall k \in \mathbb{N} \exists L \subset D : |L| \geq k$ and \prec is strict total on L .

(C2) (in-forks)

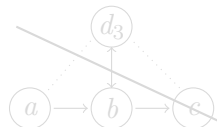
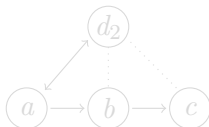
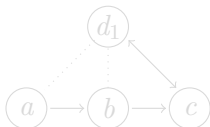
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(C3) (out-forks)

$\forall a, b, c, a \prec b \prec c, a \prec c, \exists d_2 : d_2(\prec, \succ)a, d_2 \sqcap b, d_2 \sqcap c$.

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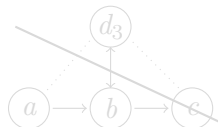
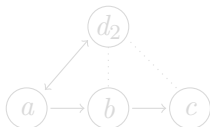
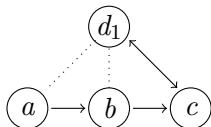
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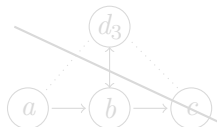
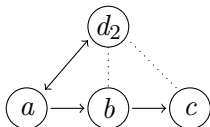
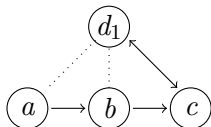
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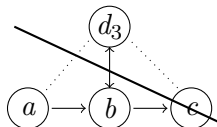
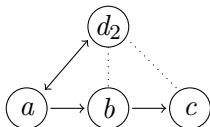
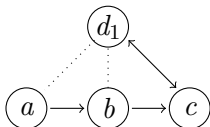
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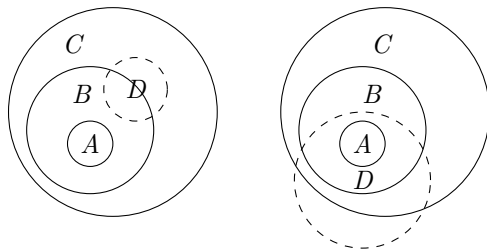
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PP is an acyclic order (\prec). (DR,PO) is incomparability relation (\sqcap).



$A \prec B, B \prec C, A \prec C.$

In-fork: $D \sqcap A, D \sqcap B, D \prec C.$

Out-fork: $A \prec D, B \sqcap D, C \prec D.$

Main Theorem

Definition

Let \mathcal{H} be the set of partition schemes \mathcal{B} such that

- (1) $\text{CSP}(\mathcal{B})$ is in P, and
- (2) \mathcal{B} contains acyclic order \prec and relation \sqcap satisfying C1-C4.

Theorem

If $\mathcal{B} \in \mathcal{H}$, then $\text{CSP}(\mathcal{B}^{\vee=})$ is NP-complete.

Main Theorem

In $\text{CSP}(\mathcal{B}^{\vee=})$ - B each variable occurs in at most B constraints.

Theorem

If $\mathcal{B} \in \mathcal{H}$, then $\text{CSP}(\mathcal{B}^{\vee=})$ -3 is NP-complete.

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Main Theorem

3-SAT asks whether a Boolean formula in 3-CNF is satisfiable:

$$(x_1 \vee x_2 \vee \neg x_3) \wedge (\neg x_1 \vee \neg x_2 \vee x_4) \wedge (\neg x_2 \vee x_3 \vee \neg x_4).$$

Exponential Time Hypothesis (ETH)

3-SAT is not solvable in subexponential time.

Theorem

If $\mathcal{B} \in \mathcal{H}$, then $\text{CSP}(\mathcal{B}^{\forall=})\text{-3}$ is not solvable in subexponential time, unless the ETH fails.

3-NAE-SAT asks whether variables can be assigned values 0, 1 so that no clause contains all equal values.

$$(a \vee b \vee c) \wedge (a \vee b \vee d) \wedge (b \vee c \vee d).$$

If $\mathcal{B} \in \mathcal{H}$, we can define a *gadget* $G(a, b, c, z_1, z_2)$ which ensures that $(a \prec b \prec c) \vee (a \succ b \succ c)$. Define instance I of $\text{CSP}(\mathcal{B}^{\vee=})$:

- 1 Add the variable M to I .
- 2 For each variable a , add constraints $a(\prec, \succ)M$ to I .
- 3 For each clause $(a \vee b \vee c)$:
 - add five variables z, x_1, x_2, x_3, x_4 to I ;
 - add constraints $a(\prec, \succ)b, b(\prec, \succ)c, a(\prec, \succ)c$;
 - add constraints $G(a, M, z, x_1, x_2)$ and $G(b, z, c, x_3, x_4)$.

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- 1 Add the variable M to I .
- 2 For each variable a , add constraints $a(\prec, \succ)M$ to I .
- 3 For each clause $(a \vee b \vee c)$:
 - a add five variables z, x_1, x_2, x_3, x_4 to I ;
 - b add constraints $a(\prec, \succ)b, b(\prec, \succ)c, a(\prec, \succ)c$;
 - c add constraints $G(a, M, z, x_1, x_2)$ and $G(b, z, c, x_3, x_4)$.

Application: Allen's Interval Algebra

Basic relation		Example	Endpoints
x precedes y	p	xxx	$I^+ < J^-$
y preceded by x	p^{-1}	yyy	
x meets y	m	xxxx	$I^+ = J^-$
y met-by x	m^{-1}	yyyy	
x overlaps y	o	xxxx	$I^- < J^- < I^+$,
y overl.-by x	o^{-1}	yyyy	$I^+ < J^+$
x during y	d	xxx	$I^- > J^-$,
y includes x	d^{-1}	yyyyyyy	$I^+ < J^+$
x starts y	s	xxx	$I^- = J^-$,
y started by x	s^{-1}	yyyyyyy	$I^+ < J^+$
x finishes y	f	xxx	$I^+ = J^+$,
y finished by x	f^{-1}	yyyyyyy	$I^- > J^-$
x equals y	\equiv	xxxx yyyy	$I^- = J^-$, $I^+ = J^+$

Let \prec be p and
 \sqcap be $\mathcal{A} \setminus \{p, p^{-1}\}$.

(C1) xxx yyy zzz ...

(C2) uuuuuu

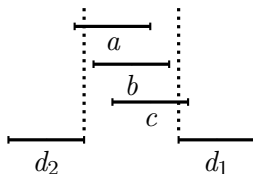
(C3) vvvvvv

(C4) www www

Application: Unit Interval Algebra

Basic relation		Example	Endpoints
x precedes y	\mathbf{p}	xxx	$I^+ < J^-$
y preceded by x	\mathbf{p}^{-1}	yyy	
x meets y	\mathbf{m}	xxxx	$I^+ = J^-$
y met-by x	\mathbf{m}^{-1}	yyyy	
x overlaps y	\mathbf{o}	xxxx	$I^- < J^- < I^+$,
y overl.-by x	\mathbf{o}^{-1}	yyyy	$I^+ < J^+$
x equals y	\equiv	xxxx yyyy	$I^- = J^-$, $I^+ = J^+$

- Choosing \prec to be \mathbf{p} does not work here.
- Instead, let \prec be \mathbf{o} and \sqcap be $(\mathbf{p}, \mathbf{p}^{-1})$.
- Conditions C1-C4 hold.



Upper Bounds

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- Branching solves $\text{CSP}(\mathcal{B}^{\vee=})$ in $2^{O(n^2)}$ time.
- For AIA, UIA, RCC-8, RA, there is a $2^{O(n \log n)}$ algorithm.
- Open Question: Is there a tighter lower bound or an improved algorithm for $\text{CSP}(\mathcal{B}^{\vee=})$?

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